

**CLAIM AMENDMENTS**

**1.** (Original) A drive system switching control method of a four-wheeled vehicle for switching two drive systems, a two-wheel drive and a four-wheel drive, comprising the steps of:

detecting a steering angle; and  
inhibiting the drive system switching if the detected steering angle is over a predetermined angle.

**2.** (Currently Amended) A drive system switching control method of a four-wheeled vehicle for switching two drive systems, a two-wheel drive and a four-wheel drive, comprising the steps of:

detecting a steering angle and a vehicle speed;  
comparing the detected steering angle and vehicle speed with a corresponding relationship between the steering angle and the vehicle speed; analyzing a predetermined drive system switching so as to determine whether or not the drive system switching is allowed; and  
inhibiting the drive system switching from both two to four and four to two wheel drive modes if it is determined that the drive system switching is not allowed.

**3.** (Currently Amended) A drive system switching control method of a four-wheeled vehicle for switching two drive systems, a two-wheel drive and a four-wheel drive, comprising the steps of:

detecting a steering angle and a vehicle speed;  
comparing the detected vehicle speed with a relationship of an allowable steering angle; analyzing the drive system switching in correspondence to a predetermined vehicle speed so as to determine an allowable steering angle in correspondence to the vehicle speed; and  
inhibiting the drive system switching from both two to four and four to two wheel drive modes if the detected steering angle is over the determined allowable steering angle.